Autonics

Ø50mm Shaft type Magnetic Multi-turn **Absolute Rotary Encoder** MGAM50S SERIES

INSTRUCTION MANUAL







Thank you for choosing our Autonics product. Please read the following safety considerations before use.

Safety Considerations

×Please observe all safety considerations for safe and proper product operation to avoid hazards.

▲ Warning Failure to follow these instructions may result in serious injury or death ↑ Caution Failure to follow these instructions may result in personal injury or product damage.

- I. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)

 Failure to follow this instruction may result in fire, personal injury, or economic loss.
- Install on a device panel to use.Failure to follow this instruction may result in fire.
- 3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.

 4. Check 'Connections' before wiring. Failure to follow this instruction may result in fire.

 5. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

▲ Caution

- Use the unit within the rated specifications.
 Failure to follow this instruction may result in fire or product damage.
 Do not short the load.
- Failure to follow this instruction may result in product damage by fire
- 3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, or salinity may be present.

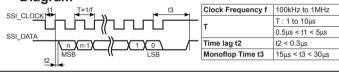
 Failure to follow this instruction may result in fire or explosion.

 4. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

Ordering Information

MGAM50S	8	- 10			·	- PN	- 24
lltem	Shaft diameter	Single- turn	Multi-turn	Output code	Rotation direction	Control output	
50mm Shaft type	Ø8mm	(/8192	Binary Code	F: Output increases by CW rotation direction at the shaft R: Output increases by CCW rotation direction at the shaft	NPN open	12-24VDC ±5%

Synchronous Serial Interface (SSI) Output Timing **Diagram**

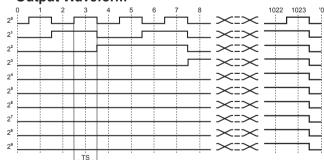


■ Synchronous Serial Interface (SSI) Data Output

*\CVP\M112\M11\M10\M9\M8\M7\M6\M5\M4\M3\M2\M1\M0\\S9\S8\S7\S6\S5\S4\S3\S2\S1\S0\ OVE

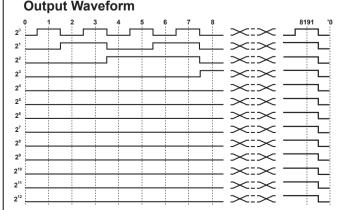
 			-	•	•
Clock	Data output name	Data	Clock	Data output name	Data
input bit	Data output frame	output bit	input bit	Data output flame	output bit
1	Over flow error bit	0 bit	15		9-bit (MSB)
2		12-bit (MSB)	16	Single-turn data	8-bit
3		11-bit	17		7-bit
4	Multi-turn count	10 bit	18		6-bit
5		9-bit	19		5-bit
6		8-bit	20		4-bit
7		7-bit	21		3-bit
8		6-bit	22		2-bit
9		5-bit	23		1-bit
10		4-bit	24		0 bit (LSB)
11		3-bit			
12		2-bit	1		
13		1-bit	1		
14		0 bit (LSB)	1		

Parallel Interface 1024-division Single-Turn Data **Output Waveform**



XTS=0.3515625°±15' *Left waveform is based on the positive logic. (The output waveform of negative logic is in reverse.)

■ Parallel Interface 8192-revolution Multi-Turn Count



 \times Left waveform is based on the positive logic. (The output waveform of negative logic is in reverse.)

- **The above specifications are subject to change and some models may be discontinued without notice.
 **Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

■ Specifications

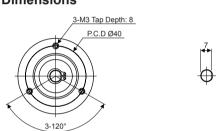
Туре				Ø50mm shaft type magnetic multi-turn absolute rotary encoder				
Model				MGAM50S8-1013-B-F-S-24	MGAM50S8-1013-B-F-PN-24			
Resolution Single-turn Multi-turn Rotation limit when power off **1		Single-turn	1024-division (10-bit)					
		Multi-turn	8192-revolution (13-bit)					
		n power off *1	±90°					
	Hysteresis		eresis	±0.1°				
		Positioning error*2		±1-bit (LSB: Least Significant -bit)				
		Output code		24-bit, Binary 2 code Binary 2 code				
4	Output	Control output		SSI (Synchronous Serial Interface) Line driver • [Low]-Sink current: Max. 20mA, Residual voltage: Max. 0.5VDC:= [High]-Sink current: Max. 20mA, Output voltage: Min. 2.5VDC:=				
on		Output signal		Single-turn data, Multi-turn count, over flow alarm (OVF) ^{×3}				
cati		Output logic		_	Negative logic output			
specification		Response time (rise/fall)		_	Max. 1μs (cable: 2m, I sink = 20mA)			
<u>18</u>	Multi-tu	rn Input level		0-1VDC				
Electrical	count re	set	Input logic	Low Active, OPEN for common use				
<u> </u>	input**		Input time	Over 100ms				
ш	SSI Clo	SSI Clock Input level		5VDC ±5%				
	input Input frequency		out frequency	100kHz to 1MHz				
	Max. re	Max. response frequency		-	30kHz			
	Power s	ver supply		12-24VDC== ±5% (ripple P-P: max.	5%)			
	Current	Current consumption		Max. 150mA (disconnection of the load)	Max. 100mA (disconnection of the load)			
	Insulation	n res	istance	Over 100MΩ (at 500VDC between all terminals and case)				
	Dielectr	ric strength		750VAC 50/60Hz for 1 minute (between all terminals and case)				
	Connec	tion		Axial cable type (cable gland)				
		Start	ing torque	Max. 70gf·cm (0.0069N·m)				
	chanical		ent of inertia	Max. 80g·cm² (8×10 ⁻⁶ kg·m²)				
spe	cification	Shaf	t loading	Radial: 10kgf, Thrust: 2.5kgf				
		Max.	revolution*5	3000rpm				
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, 2 direction for 2 hours					
Shock			Approx. Max. 50G					
Environ- Ambient temp.			-10 to 70°C, storage: -25 to 85°C					
ment Ambient humi.			35 to 85%RH, storage: 35 to 90%RH					
Protection structure			ıre	IP50 (IEC standard)				
Cable			Ø6mm 10-wire, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 19, insulator diameter: Ø0.8mm)	Ø6mm 17-wire×2, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 17, insulator diameter: Ø0.8mm)				
Accessories			Mounting bracket, coupling					
Apı	proval			CE				
Weight ^{*6}				Approx. 391g (approx. 261g)	Approx. 523g (approx. 393g)			

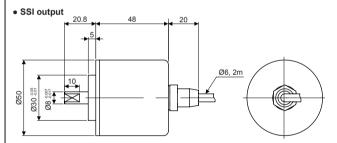
- ※1: It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no overrated revolution occurred since proper multi-turn counts may not be available if any revolutions occurred.
- over ±90° from the position when power is off. ※2: When turning ON/OFF the unit, there may be ±1-bit (LSB) error at present position by hysteresis
- 33: OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolution).
 44: Multi-turn count shall be initialized as ^r0 revolution when multi-turn count reset is input.
 5: In case of Parallel type model, Make sure that Max. response revolution should be lower than or equal to max, allowable revolution when selecting the resolution.

[Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$]

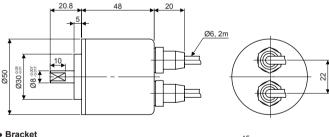
※6: The weight includes packaging. The weight in parenthesis is for unit only.
※Environment resistance is rated at no freezing or condensation.

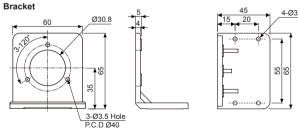
Dimensions



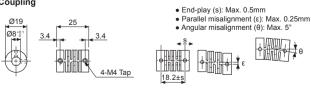


Parallel output





Coupling



- Do not load overweight on the shaft
- For more information about flexible coupling (ERB Series), please refer to the catalogue

- Do not put strong impact when insert a coupling into shaft.
 Failure to follow this instruction may result in product damage.
 Fix the unit or a coupling by a wrench under 0.15 N·m of torque.

 When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle

Functions

Multi-turn count reset

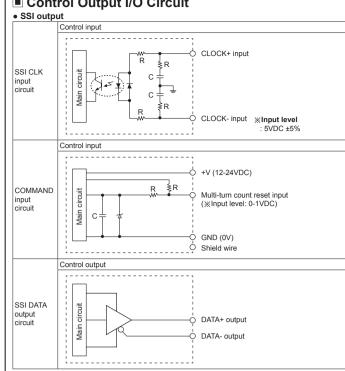
Multi-turn data will be reset as Γ revolution $0_{
m J}$ when multi-turn count reset cable (light purple) is inputted 0 to 1V (over 100ms)

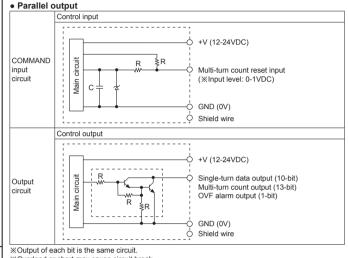
Over flow alarm (OVF)

Using a larm function when multi-turn count is out of rotation ranges (0 to 8191 revolutions).

Over flow alarm is also reset with multi-turn count value when multi-turn count reset signal (light purple) is inputted.

Control Output I/O Circuit





※Overload or short may cause circuit break

Connections

(unit: mm)

SSI output					
Cable					
Cable color	Description				
Brown		CLOCK+			
Red	SSI	CLOCK-			
Orange	331	DATA+			
Yellow		DATA-			
Green		Multi-turn count reset			
Blue	COMMAND	N.C.			
Purple	COMMAND	N.C.			
Gray		N.C.			
White	+V (12-24VDC)				
Black	GND (0V)				
Shield wire	Signal shield cable (F.G.)				

Parallel output

Multi-turn coι	int cable (Sheath c	olor: Black)	Single-turn data cable (Sheath color: Gray)			
Cable color	Description		Cable color	Description		
Brown		2°	Brown		2°	
Red	7	2 ¹	Red	Single-turn data	2 ¹	
Orange		2 ²	Orange		2 ²	
Yellow		2 ³	Yellow		2 ³	
Green		2 ⁴	Green		2 ⁴	
Blue	T	2 ⁵	Blue		2 ⁵	
Purple	Multi-turn — count	2 ⁶	Purple		2 ⁶	
Gray	Count	27	Gray		27	
Pink		2 ⁸	Pink		2 ⁸	
Clear		2 ⁹	Clear		2 ⁹	
Light brown		2 ¹⁰	Light brown	N.C.		
Light yellow	7	2 ¹¹	Light yellow			
Light green		2 ¹²	Light green	N.C.		
Light blue	OVF	OVF		N.C.		
Light purple	Multi-turn count re	Multi-turn count reset		N.C.		
White	N.C.		White	+V (12-24VDC)		
Black	N.C.		Black	GND (0V)		
Shield wire	Signal shield cable (F.G.)		Shield wire	Signal shield cable (F.G.)		

- **Do the wiring properly.
 **Encoder's metal case and shield cable must be grounded (F.G.).
- **Do the wiring with care for short since dedicated Driver IC is used for I/O circuit.

 **Do not apply tensile strength over 30N to the cable.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal. 4. Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines,
- to prevent inductive noise. 7. Check the wire type and response frequency when extending wire because of distortion of
- waveform or residual voltage increment etc by line resistance or capacity between lines.

 8. This unit may be used in the following environments.
- (Indoors (in the environment condition rated in 'Specifications') ②Altitude max. 2,000m ③Pollution degree 2
- (4) Installation category II

Major Products

- Photoelectric Sensors Temperature Controllers Fiber Optic Sensors Temperature/Humidity Transducers
- Door Side Sensors Counters
- Area Sensors Timers
- Panel Meters
 Tachometer/Pulse (Rate)Meters
- Pressure Sensors
- Rotary Encoders Display Units Connector/Sockets Sensor Controllers
- Switching Mode Power Supplies
 Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables Stepper Motors/Drivers/Motion Controllers
 Graphic/Logic Panels
- Laser Marking System (Fiber, Co₂, Nd: YAG)
 Laser Welding/Cutting System

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